

VF-PLUME

Vertical Farming Plant Localizing UAV with Mass Estimation



UAS Research and Test Facility



Unmanned Aerial Systems (VIP)



Contents

- **Introduction/Motivation** - The Importance of Vertical Farms
- **Problem** - Monitoring Plant Growth
- **Solution** - VF-PLUME
- **Data/Analysis** - Open3D
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Introduction

- Growing population, especially in urban areas, requires more efficient farming
- Vertical Farming is a growing industry in agriculture
- Great control over environmental factors
 - Increased crop survival rate
 - Increased yield per acre
- Becoming more popular globally



*(Eden Green Technology, 2023),
(iFarm, 2023)*

The Problem: How Do We Track Growth of Plants?

- Wish to monitor environment and plants to ensure high yields
- Previous monitoring techniques
 - Human observation
 - Stationary sensors/cameras
- Human monitoring requires time and effort
- Monitoring system requires capital and maintenance



The Solution

“VF-Plume”

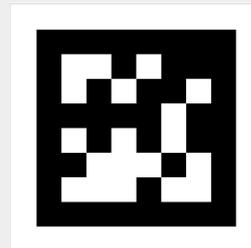
1. Drone Localization
2. Point Cloud Segmentation
3. Plant Mass Estimation
4. Environmental Data Collection



VF-Plume

Drone Localization: April Tags

- April Tags - provide 2D-plane reference in 3D space
- From recorded rosbag of drone's camera capture and motion, AprilTags locations (x,y) were noted
- Visualized and plotted dense areas of AprilTags as Pointcloud using Open3D (Data & Analysis)



36h11 family AprilTag

```
- family: tag36h11
id: 19
hamming: 0
goodness: 0.0
decision_margin: 122.28094482421875
centre:
  x: 348.5095534490087
  y: 107.4391147849452
corners:
- x: 328.99011230468756
  y: 128.7822265625
- x: 369.16513061523426
  y: 126.92005920410156
- x: 368.4537658691406
  y: 85.63154602050781
- x: 327.8530273437501
  y: 87.95727539062499
homography:
- 18.321188803750772
- 2.342868085711306
- 348.5095534490087
- -1.6227066694049237
- 21.10656644238523
- 107.4391147849452
- -0.005370318728551229
- 0.00539328872905569
- 1.0
```

Unique ID for each Apriltag in family

Coordinates of Apriltag center

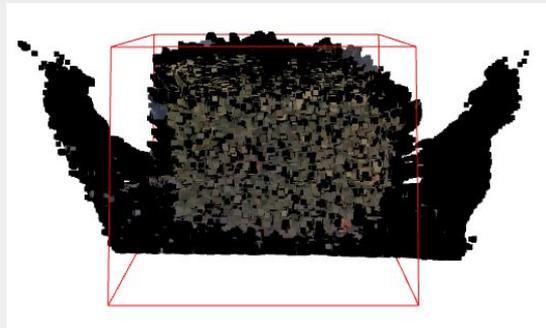
Coordinates of Apriltags' corners

Homography:

AprilTag detections output for one tag

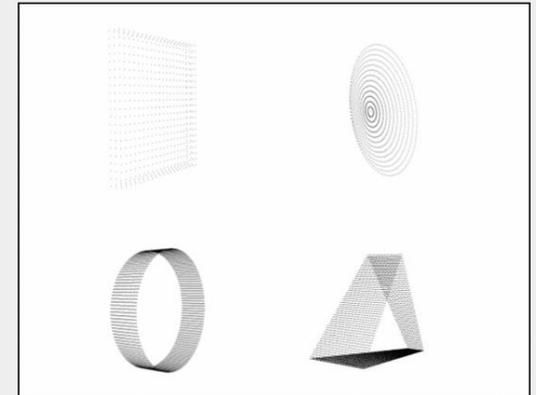
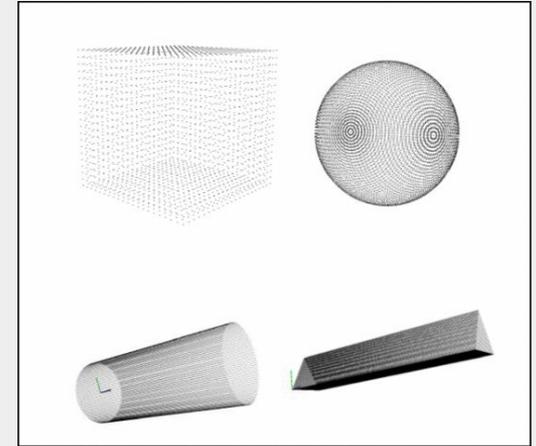
Point Cloud Segmentation

1. Filter camera color matrix for green colors
2. Create histogram for green data points in x, y, and z direction
3. Find space that does not contain lettuce by defining upper and lower bounds of histogram value
4. Use empty space to create bounding box around volume that contains lettuce



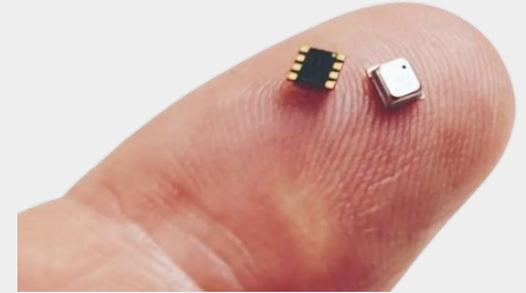
Plant Mass Estimation

1. Segment general point cloud to individual plants
2. Separate segmented point cloud into many 2D slices
3. Fit points in 2D slice to a polynomial curve
4. Integrate curve for area
5. Integrate area for volume
6. Multiply volume with density for mass estimation

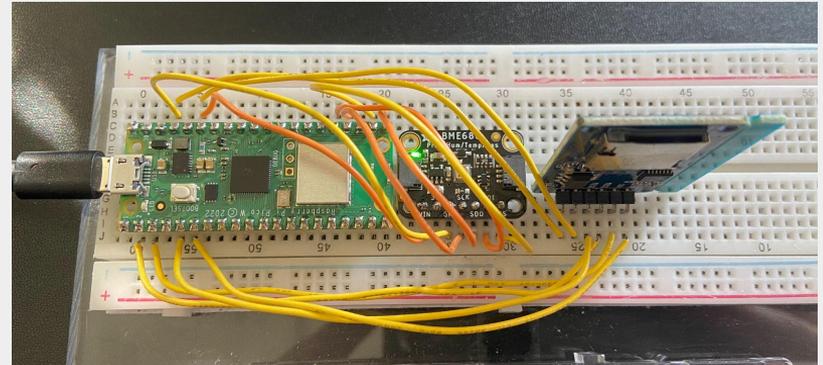


Environmental Gas Readings

- Bosch BME688
 - Temperature, Pressure, Humidity
 - Volatile Organic Compounds
 - Air Quality Index
 - Other Gasses: Carbon Monoxide, Hydrogen
- Store data for post processing
- Next steps
 - Convert to single PCB
 - System integration



Bosch BME688 Sensor



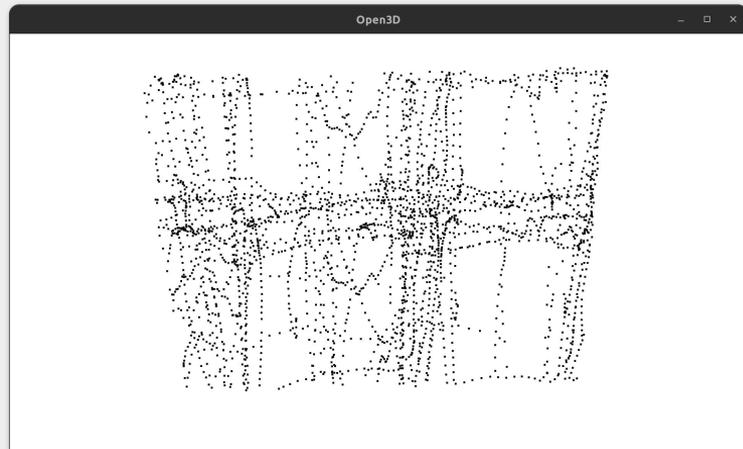
Gas Readings Circuit

Experiments, Data Analysis

- Physical data collection November 2022
 - Color camera, depth camera recordings
 - Actual April tag location
- Post processing of data
 - Open3D - Position and localization visualization
 - Masking to help with image segmentation
 - Mass estimation algorithm



Vertical Farm Test Setup



Pointcloud of Apriltags throughout flight

Future Work

Testing & Verification of Algorithms

Vehicle Robustness/Automation

- Automated monitoring, return to home, wireless charging

Interactive GUI

- 3D maps of plant growth temperature, pressure, gasses throughout farm

Data Analysis/Machine Learning

- Large amounts of data including input (temperature, pressure, presence of gasses) and output (mass of plant, plant growth rate)

Journal Publication

Works Cited

Bosch. (n.d.). *BME688 Sensor on Fingertip*. Gas Sensor BME688. Retrieved April 10, 2023, from <https://www.bosch-sensortec.com/products/environmental-sensors/gas-sensors/bme688/>.

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W. C. Chang, C. H. Wu, Y. H. Tsai and W. Y. Chiu, "Object volume estimation based on 3d point cloud", 2017 International Automatic Control Conference (CACCS), pp. 1-5, Nov 2017.

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