

# Revanth Krishna Senthilkumaran

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Plano, TX

**Permanent Resident of the USA**

**Seeking Internships and Co-ops for 2024 in Robotics,  
Embedded Software, Software Engineering, R&D**

## EDUCATION

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- **Purdue University** West Lafayette, IN  
*Junior (3rd Year), Bachelor of Science in Computer Engineering; GPA: 3.56* Aug 2021 - Dec 2024
  - **Relevant Coursework:** Reinforcement Learning, Open Source Software Senior Design, Microprocessor Systems and Interfacing, Data Structures, Computer Architecture and Prototyping, EE Fundamentals, OOP in C++, Signals and Systems, Probabilistic Methods, Python for Data Science, Advanced C Programming
  - **Awards/Honors:** Dean's List and Semester Honors - All Semesters, Third Place in Interdisciplinary Category - Purdue Spring Undergraduate Research Conference 2022, Best Data Visualization - ASA DataFest 2022

## EXPERIENCE

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- **Bechtel Innovation Design Center** West Lafayette, IN  
*Printing and Prototyping Peer Mentor* Feb 2023 - Present
  - **Makerspace:** Working with over 800 students every semester for projects with Metal and Non-metal Laser Cutting, 3D Printing: SLA, SLS, Carbon-fiber reinforced Onyx and resin, along with many personal projects.
- **Robotics, Perception and Manipulation Laboratory** Minneapolis, MN  
*Undergraduate Research Assistant* Summer 2023
  - **Spot:** Developed new method of robust data collection using Boston Dynamics robot quadruped Spot for learning from demonstration on manipulation tasks with language commands for a vision-language model (Per-Act). Project involved Python, ROS, Simulation, Camera Transformations, Voxels, Boston Dynamics API.
- **SMART Laboratory** West Lafayette, IN  
*Undergraduate Research Assistant* Feb 2022 - Aug 2023
  - **IEEE-IROS 2023:** Established novel method of using UAVs to inspect surfaces autonomously with learning from expert demonstration **accepted** to IEEE-IROS 2023: **UPPLIED**. Used WeBots simulation environment, ROS, VICON camera system to perform real world experiments.
  - **IEEE-TAC:** Paper under review at IEEE-TAC journal: **MOCAS** Dataset - mobile robot SMARTmBOT used to create a multimodal dataset with user studies for simultaneous cognitive workload assessment.
- **Air Force Research Laboratory** West Lafayette, IN  
*Undergraduate Researcher* Fall 2022 - Spring 2023
  - **NXP HoverGames3 Team Lead:** Led a team of students to compete in the NXP HoverGames3 UAV sustainability contest. Coordinated with the Horticulture department and proposed a method of using a drone with an RGB-depth camera to investigate and inspect lettuce plants grown on vertical farming, including shades of green, water content and gas sensing.
  - **IEEE Autonomous UAV Challenge 2023:** Worked with rover-tracking team to use a UAV to compete in a challenge, where a UAV tracks and follows a ground rover through obstacles.
- **The Autonomous Robotics Club of Purdue** West Lafayette, IN  
*Vice President and Project Manager of Piano Hand* Sep 2021 - Present
  - **Vice President:** Representing the largest robotics club of Purdue for the engineering councils for funding pitches, networking, forming club collaborations and organizing workshops and seminars. Co-running a robotics and autonomy expo, RISE, where student organizations and research laboratories present and demo work.
  - **Piano Hand:** Leading a team to build an autonomous human-like hand that can read sheets and play the piano.

## PROJECTS

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- **Revo BP-1:** Building a bipedal robot with  $\mu$ ROS with RTOS from scratch, incl. CAD, 3D printing and laser cutting.
- **Crazyflie 2.0:** Experimenting with Swarm UAV systems using multiple Crazyflie 2.0 UAVs with the Bitcraze VM.

## SKILLS

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**Languages:** Python, C++, C, Assembly, Verilog, SQL **Technologies:** Git, ROS, Linux, Docker, MATLAB